



kNOW
kilogram NOW

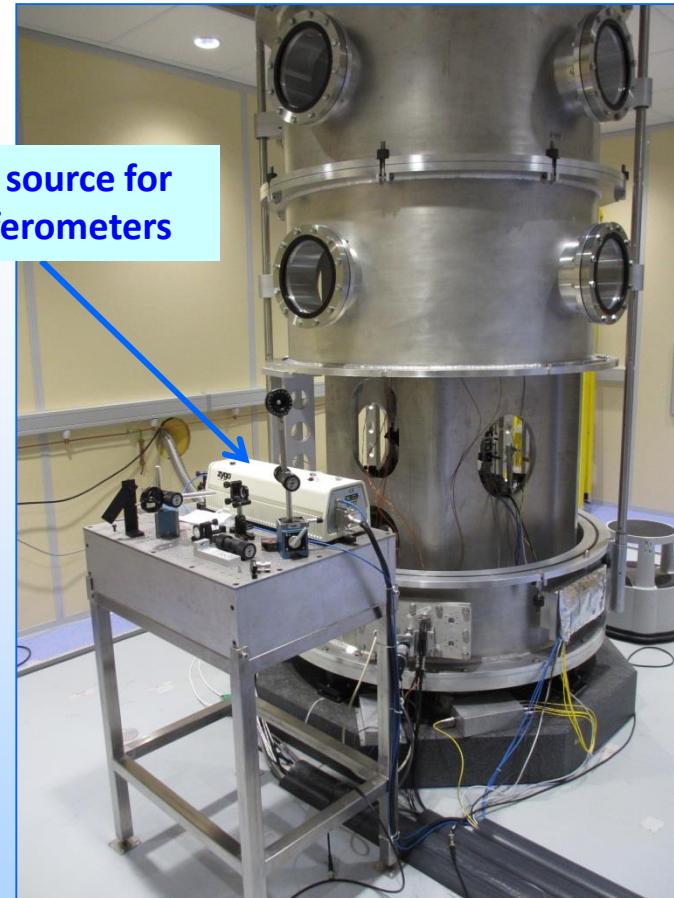
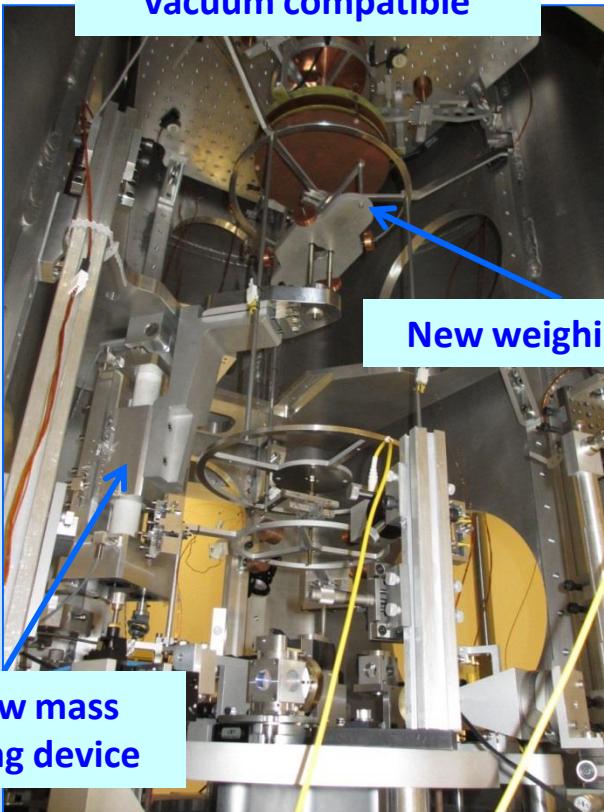
2013 workshop
Italy - Torino



Status of the BIPM Watt Balance

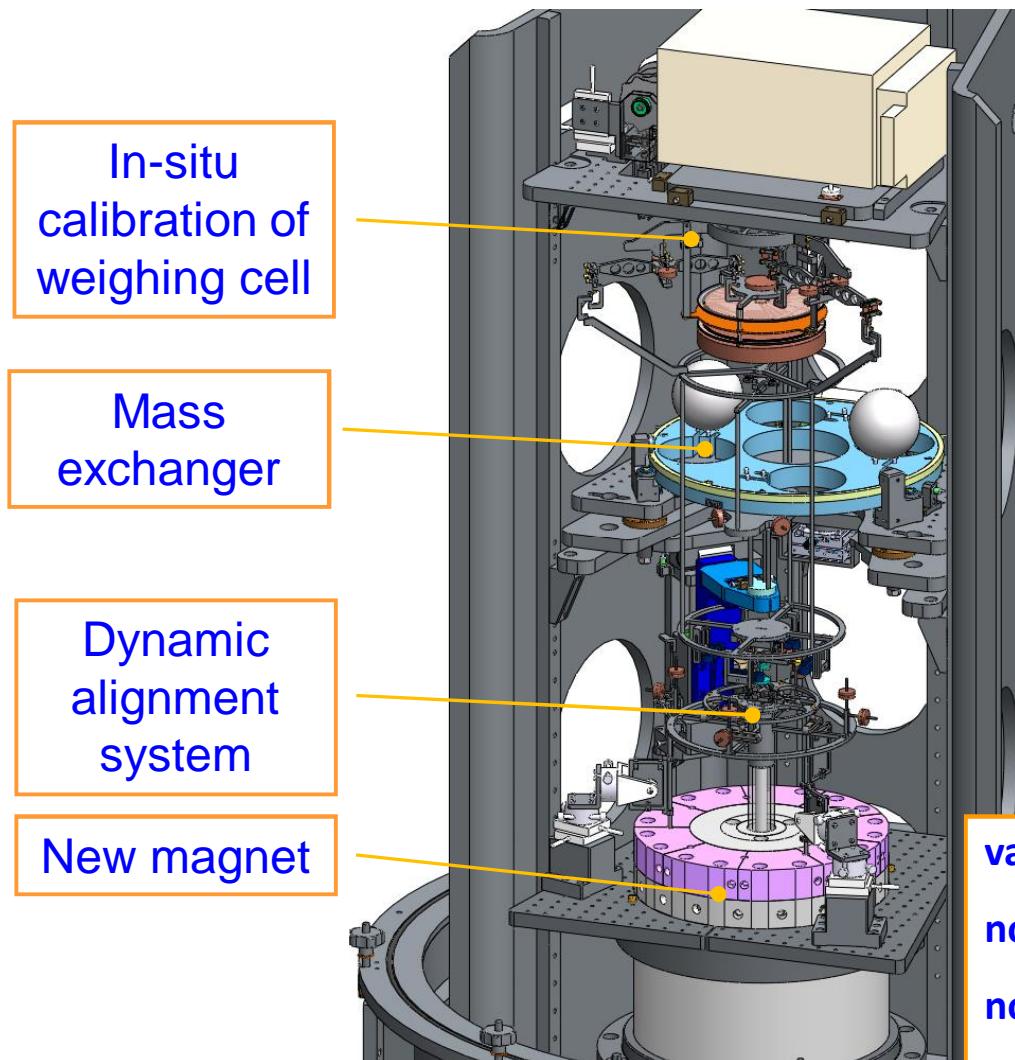
H. Fang, M. Stock

Present apparatus in the new laboratory



- “ Modifications made to accommodate the apparatus
- “ Also some new components
- “ Fully operational in air

New components for the watt balance



In-situ
calibration of
weighing cell

Mass
exchanger

Dynamic
alignment
system

New magnet

most mechanical
parts available

to be integrated into
suspension

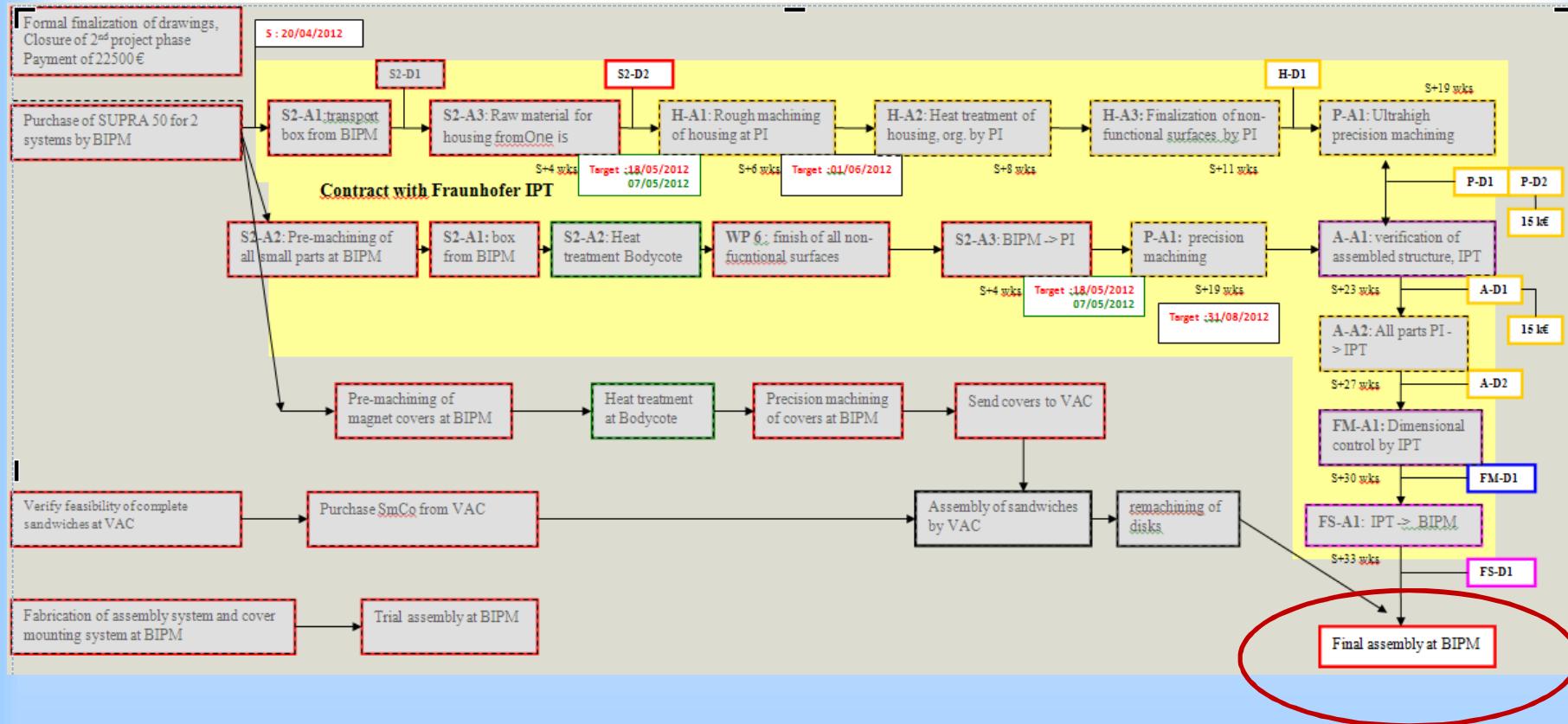
ready for
measurements in
2014

vacuum: < 0,01 Pa

no air convection; no air buoyancy

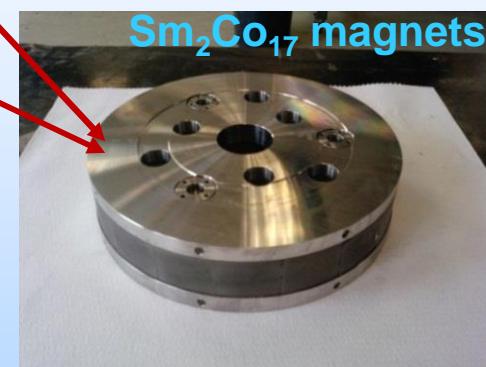
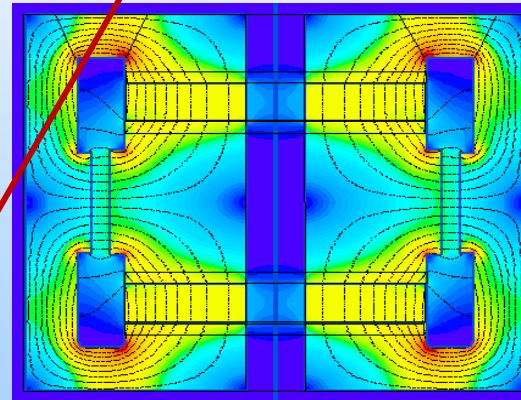
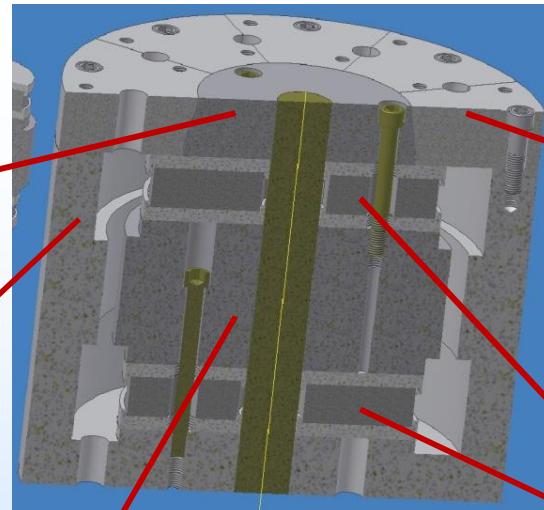
no air refractive index correction

Fabrication planning for the new magnet



Last step: assembly

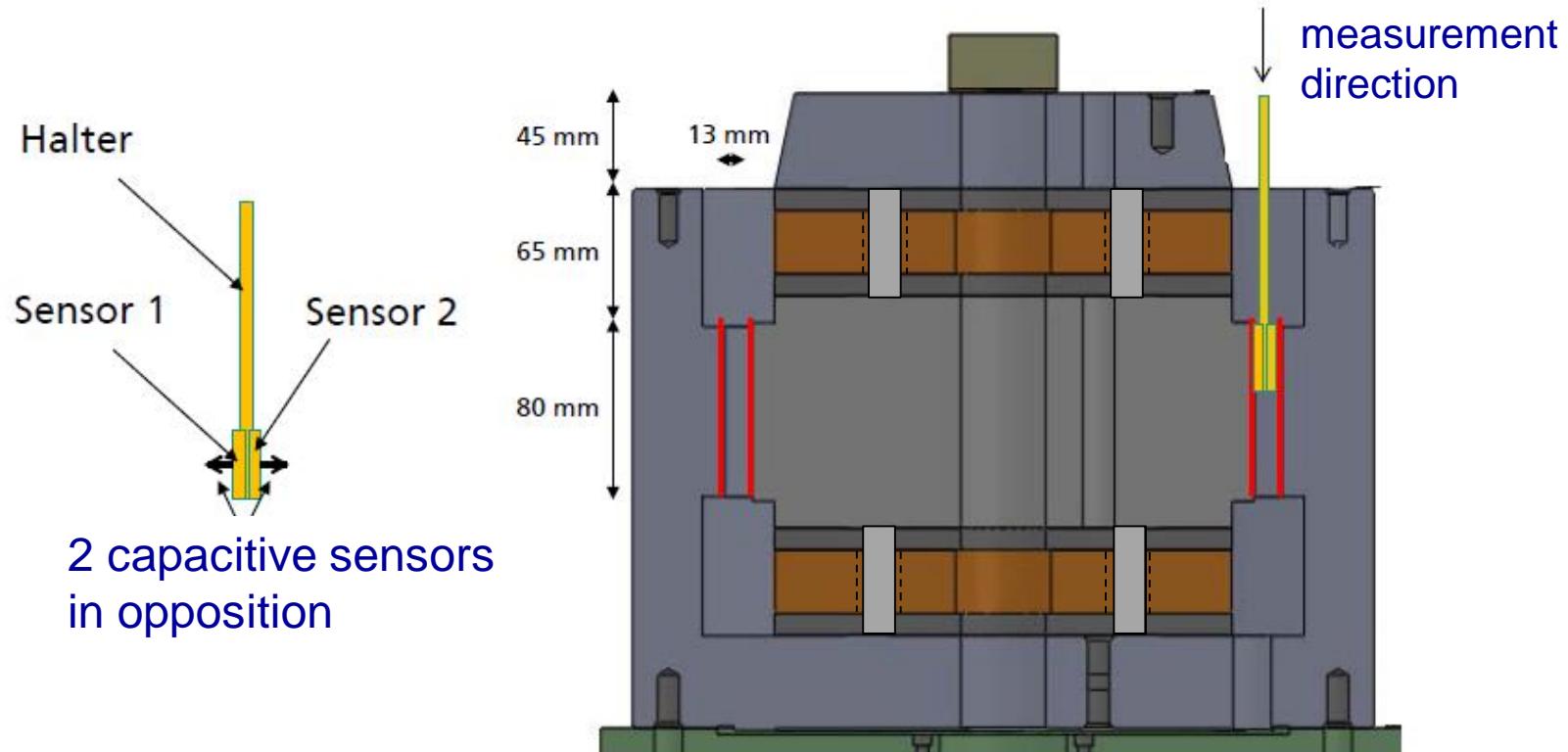
New magnet: fabrication of parts



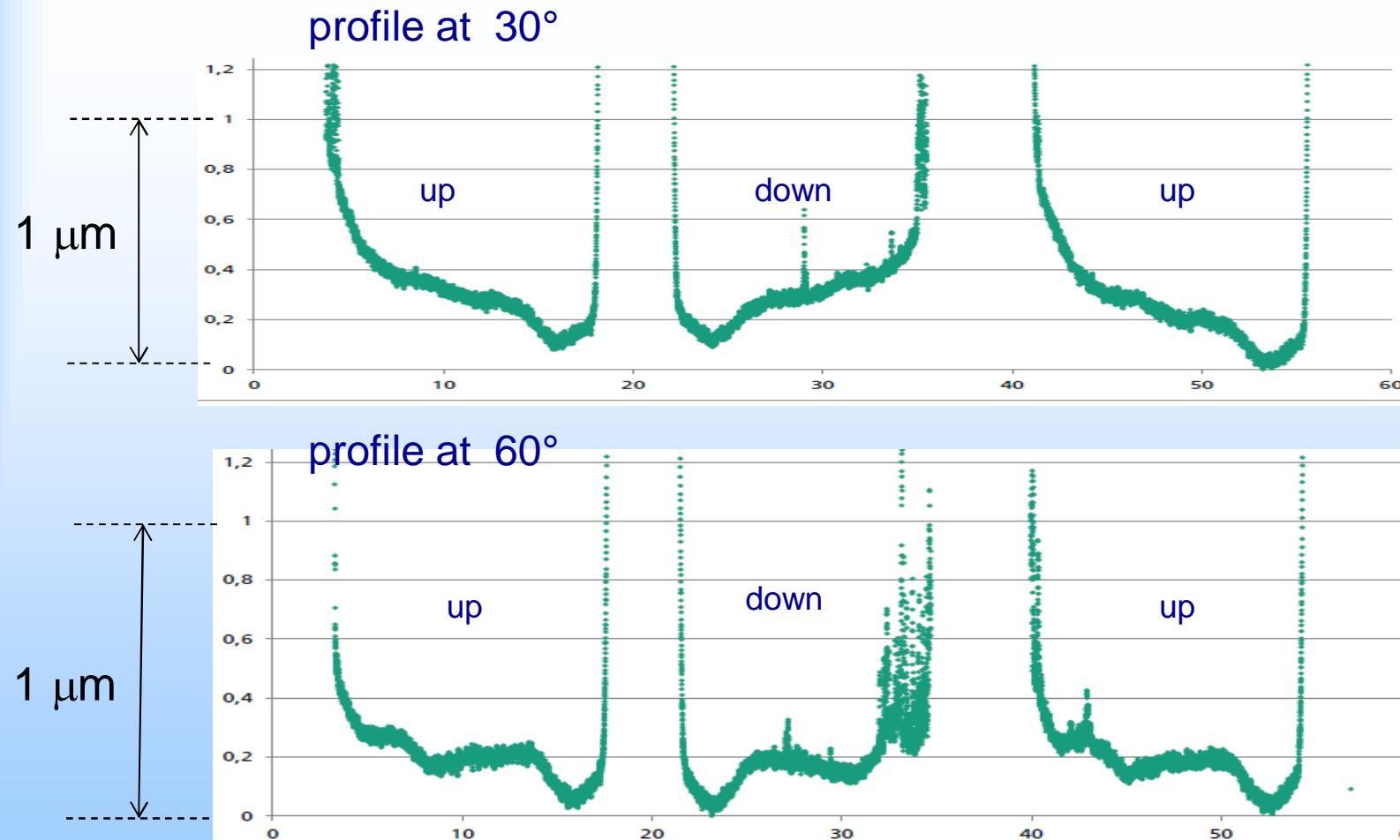
- " All parts now at BIPM
- " All components meet the specifications
- " Trial assembly (without the magnets) and uniformity of the gap width verified ($<1 \mu\text{m}$)

New magnet: verification

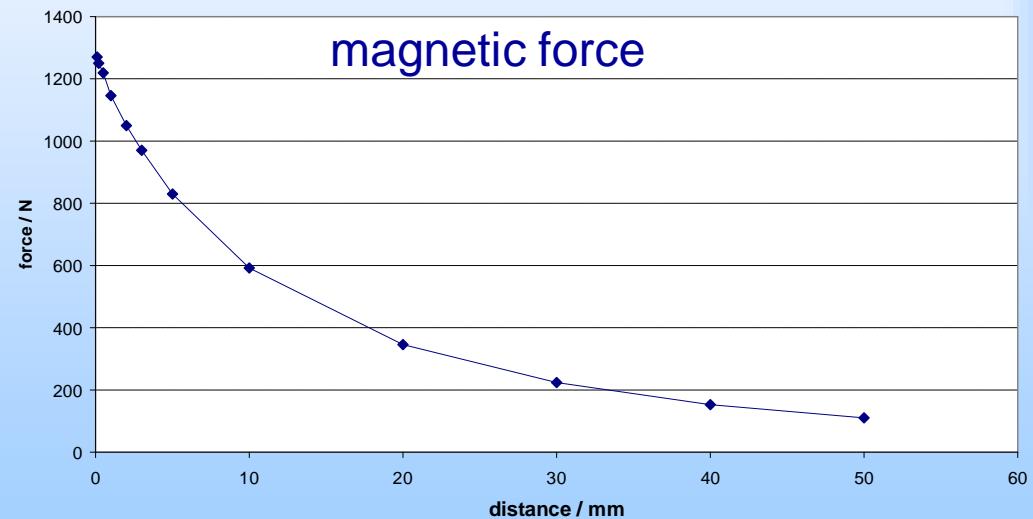
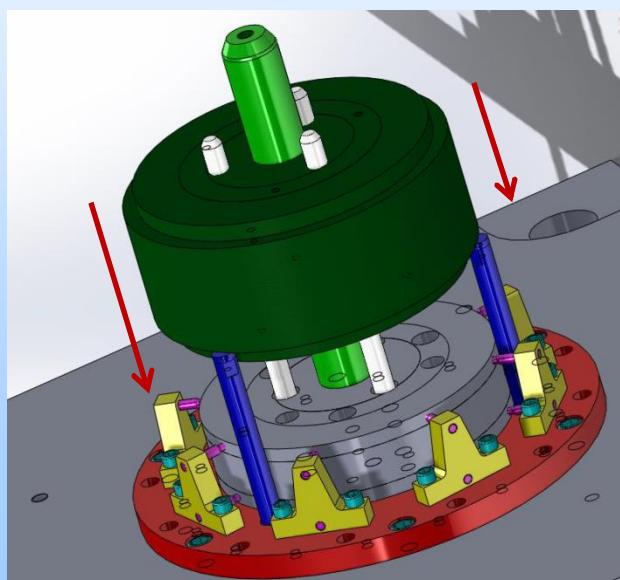
Measurement setup for gap detection (assembly without magnets)



New magnet: verification

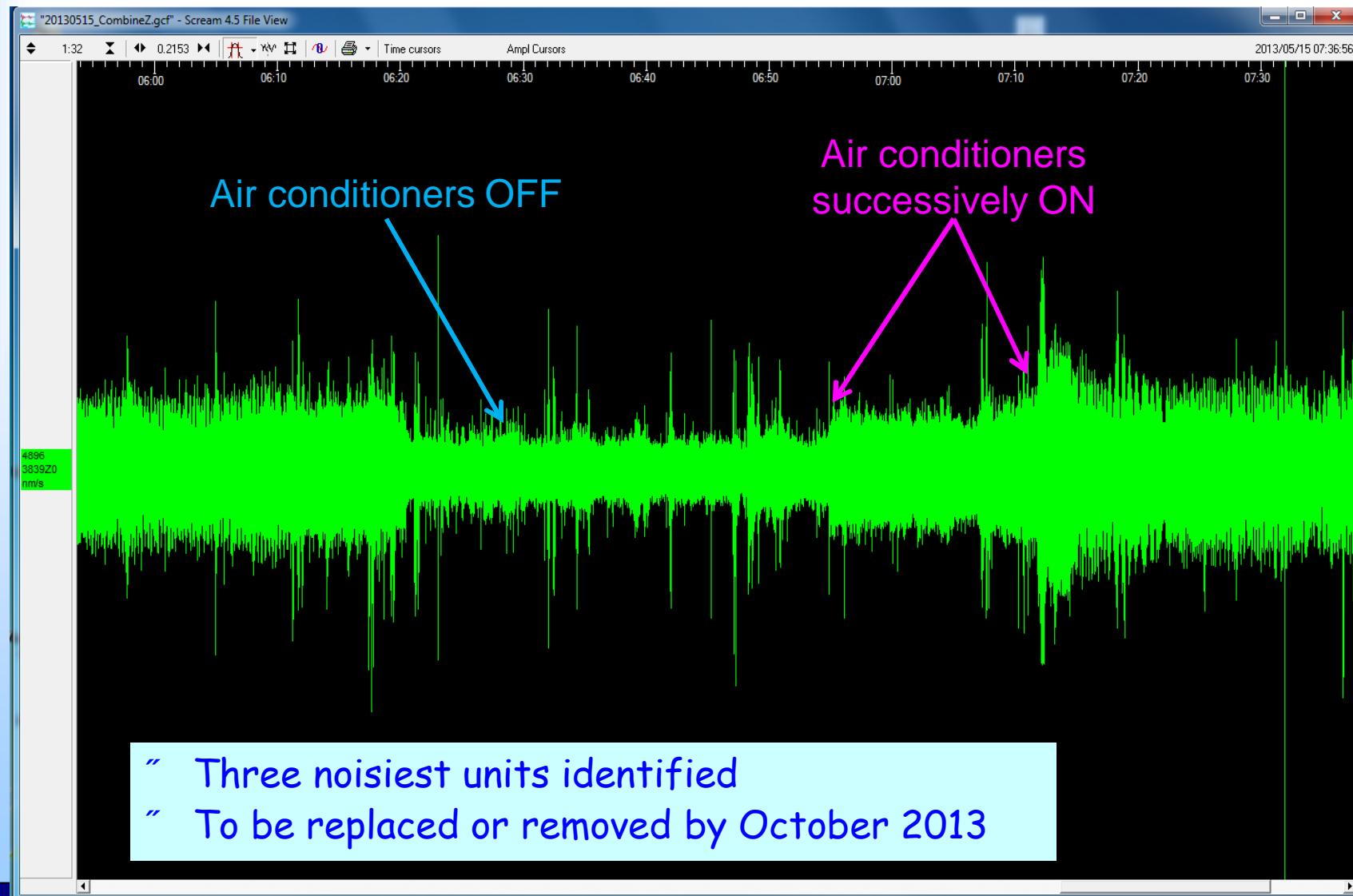


New magnet: assembly nearly finished

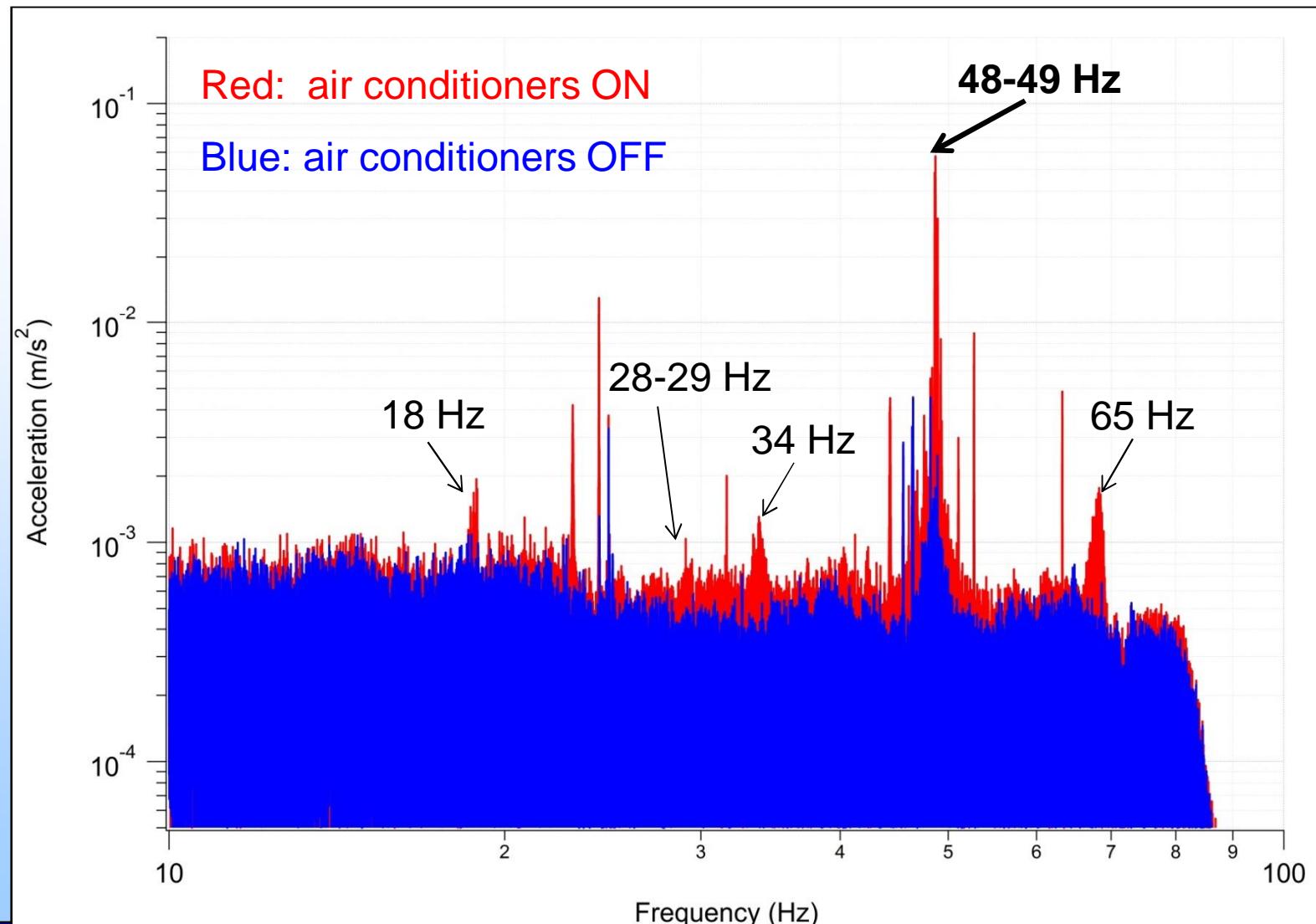


Some problems with too tight tolerances: now solved

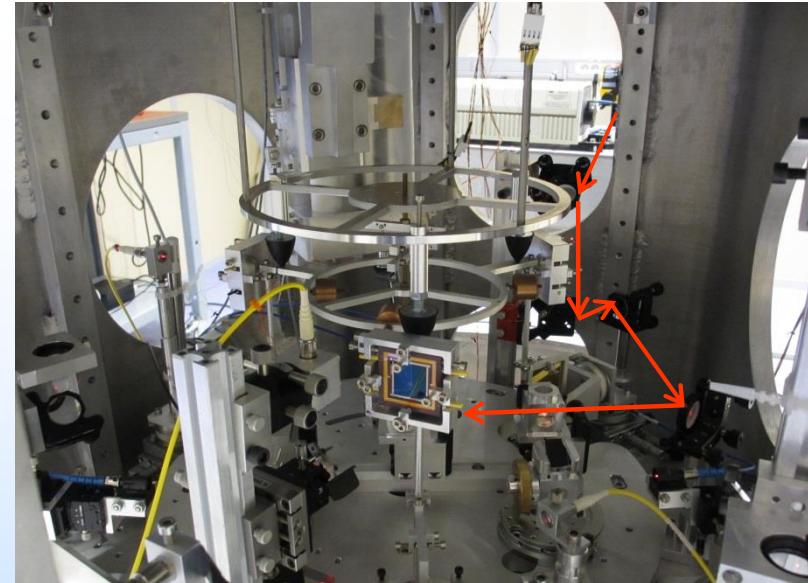
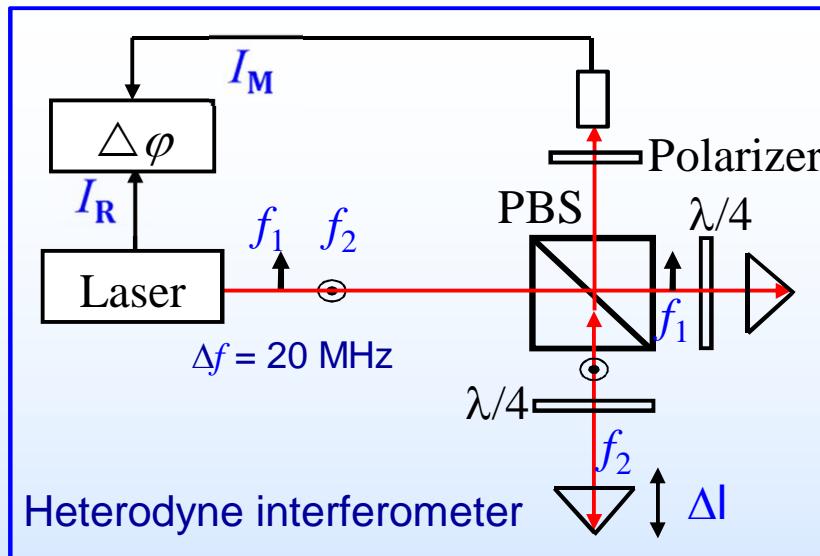
Sources of the surrounding vibration noise (1)



Sources of the surrounding vibration noise



Periodical non-linearity error (1)

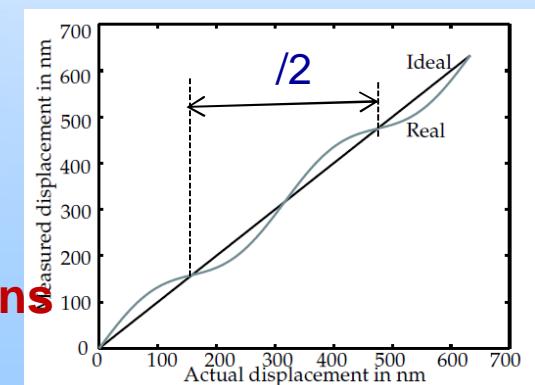


$$\Delta\phi = 4\pi \frac{\Delta l}{\lambda_2}$$

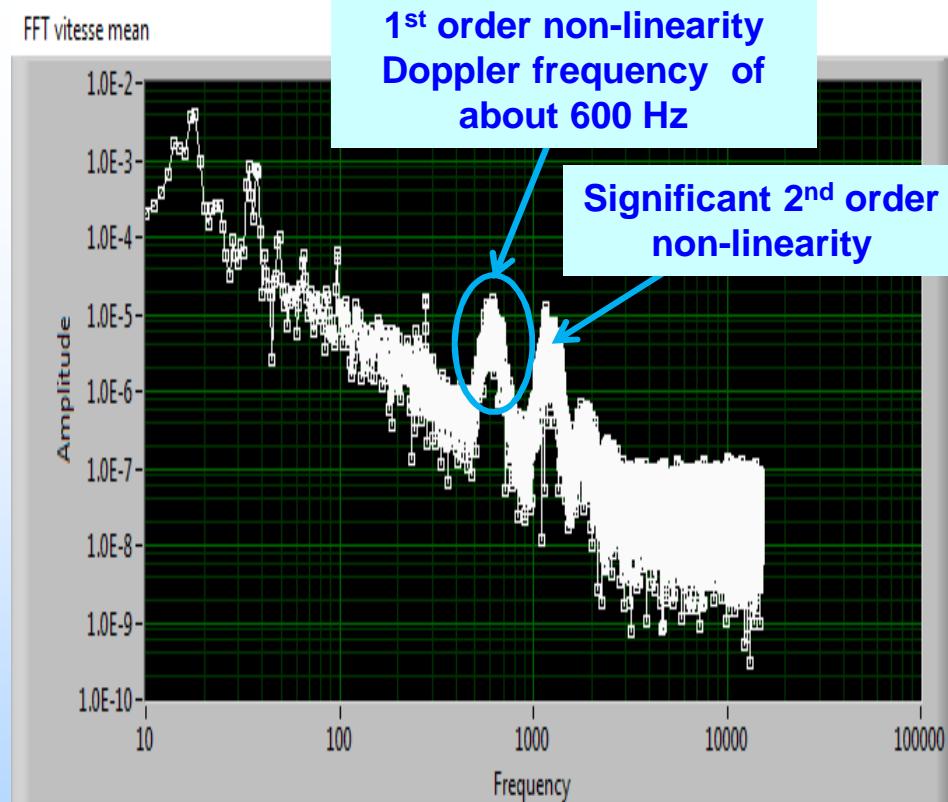
$$I_R = \frac{1}{2} E_0^2 [\cos(2\pi(f_2 - f_1)t) + \Delta\phi_0]$$

$$I_M = \frac{1}{2} E_0^2 [\cos(2\pi(f_2 - f_1)t) + \Delta\phi_0 + \Delta\phi + \Delta\phi_{nl}(\Delta\phi)]$$

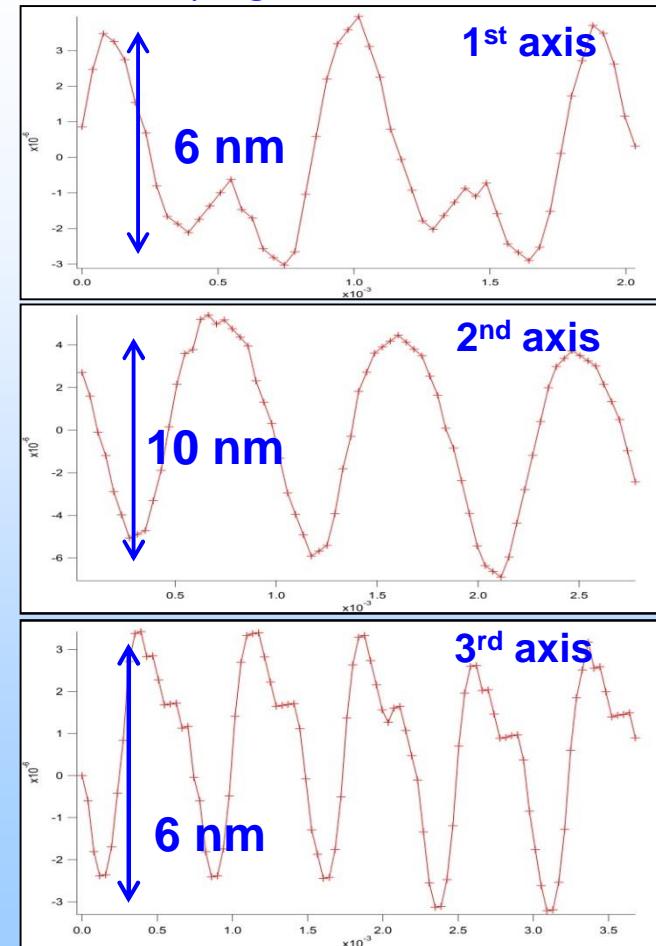
**Extra phase term: periodic deviations
(optical quality & alignment)**



Periodical non-linearity error (2)



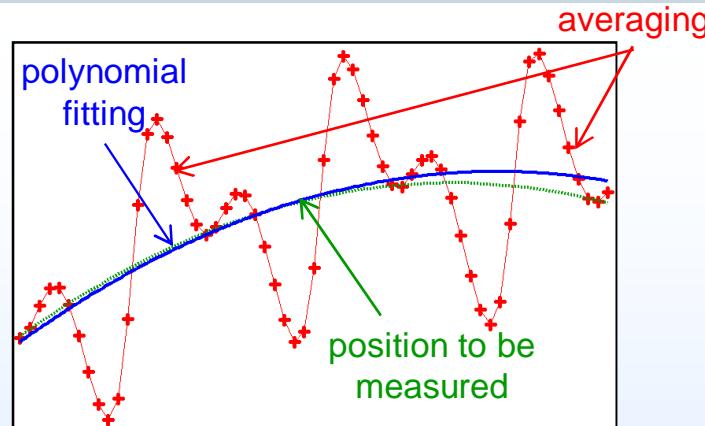
Example of the observed
non-linearity errors
(sampling rate of 25 kHz)



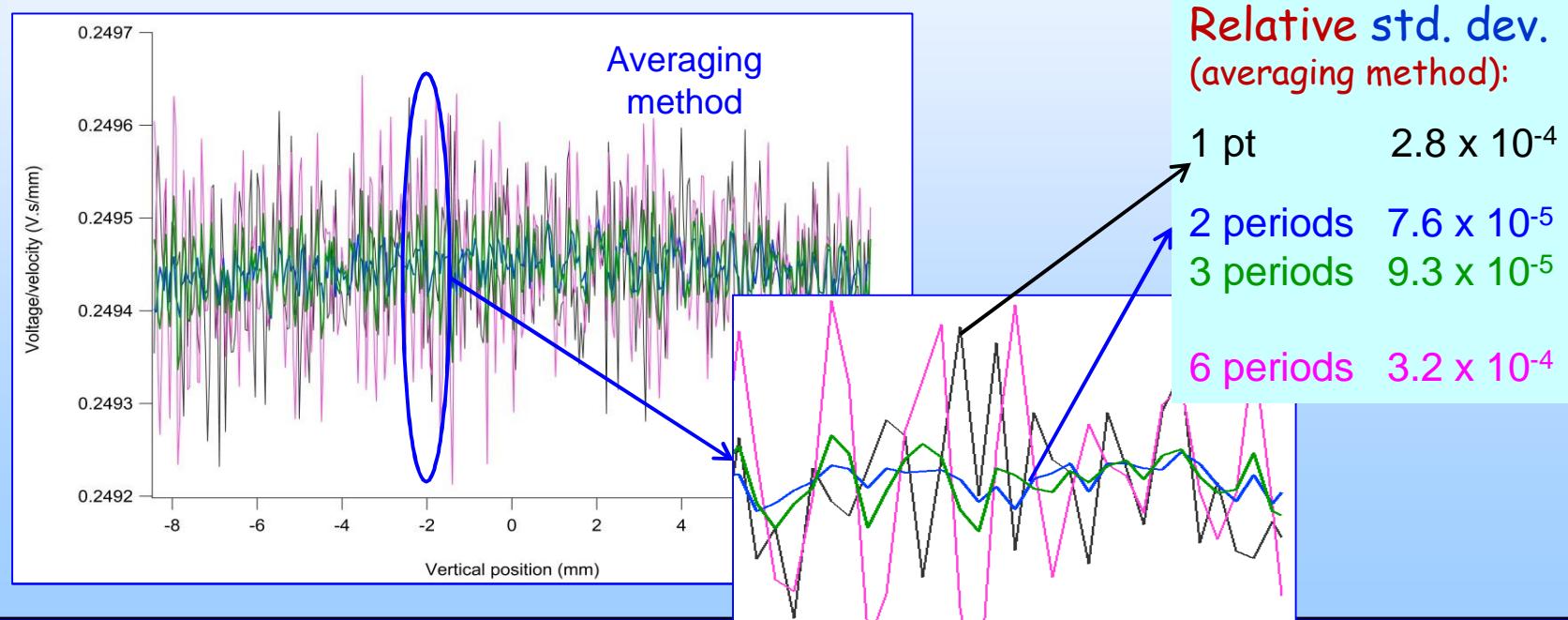
short term: - better alignment
- mathematical reduction

long term: - new interferometer (2014)
with physical separation of beams

Reduction by mathematical methods



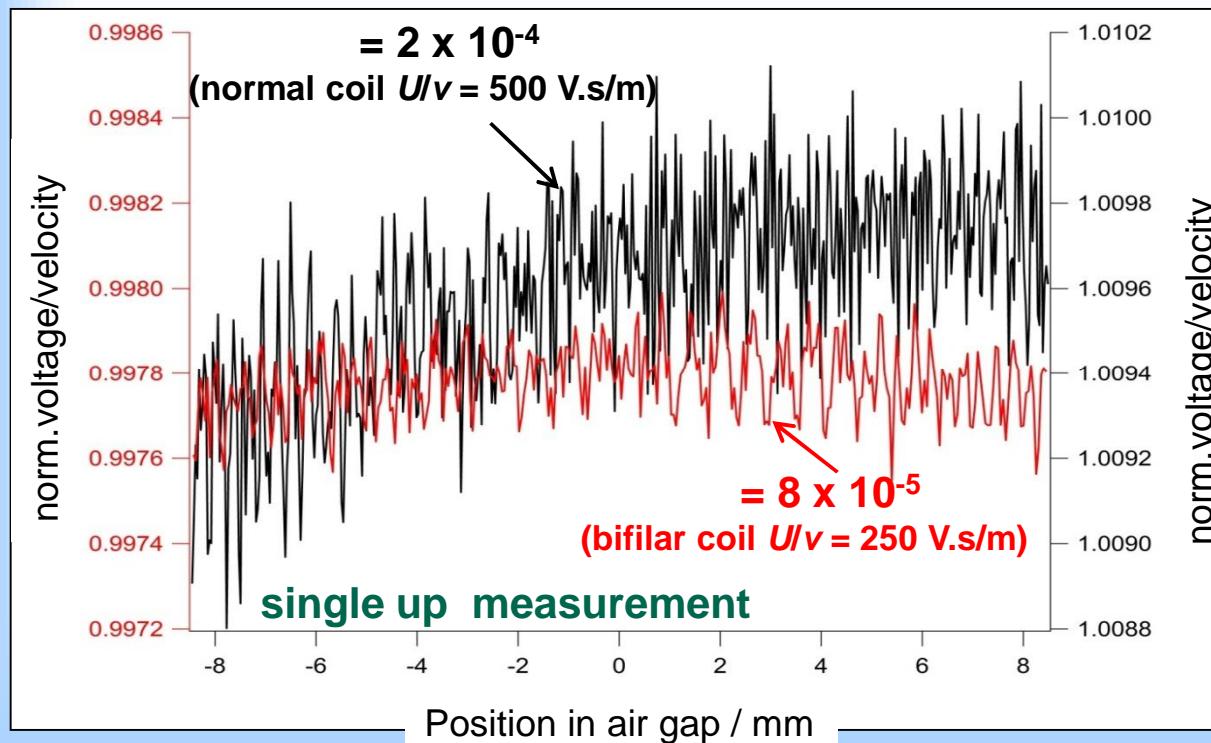
- “ Various methods evaluated
- “ Two of them (averaging and polynomial fitting) used
- “ Gave similar results in the present measurement conditions



Voltage-to-velocity ratio

voltage-to-velocity ratio $\frac{U}{v} = BL$

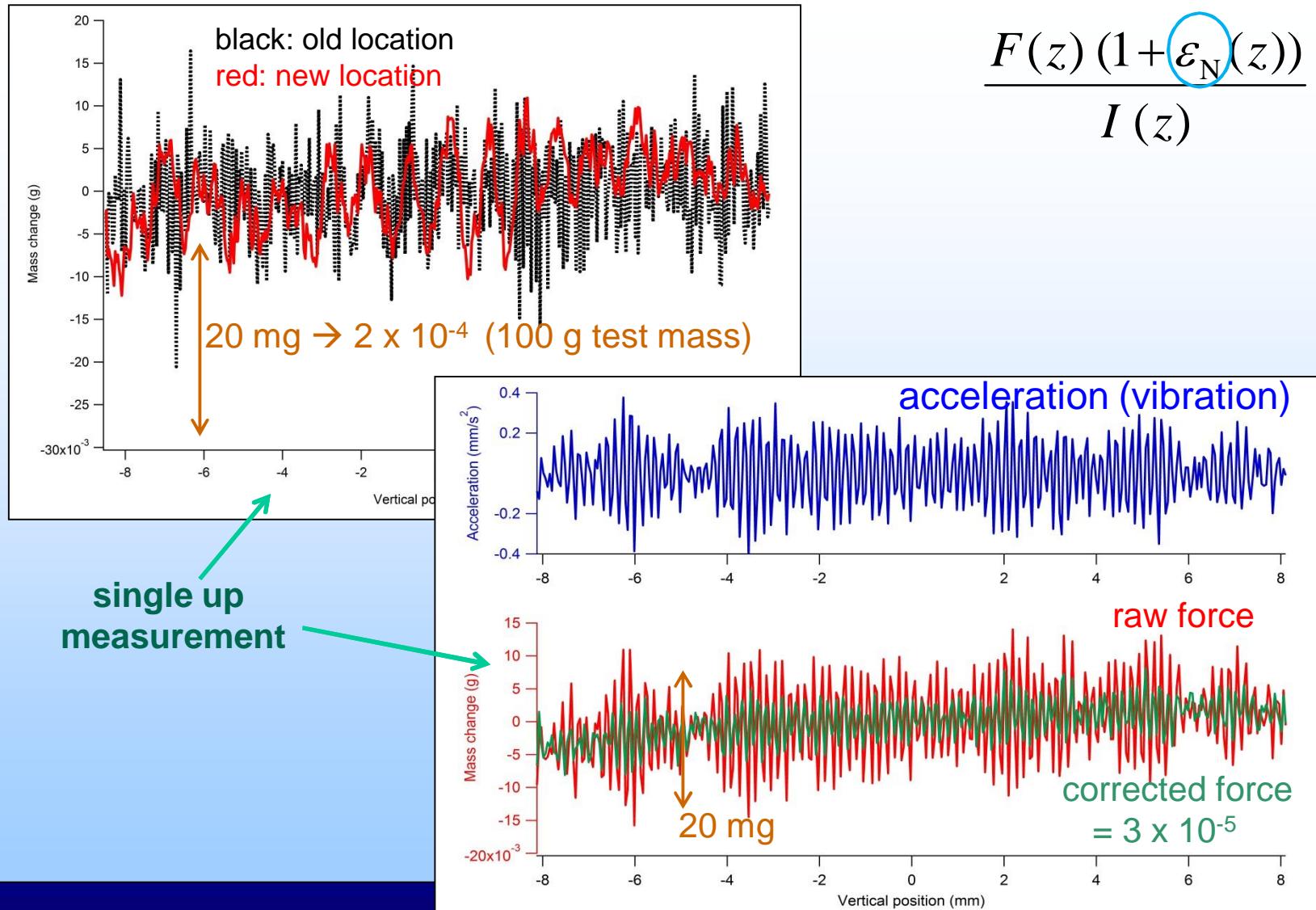
$$\frac{U(z) (1 + \mathcal{E}_N(z))}{v(z) (1 + \mathcal{E}_N(z))}$$



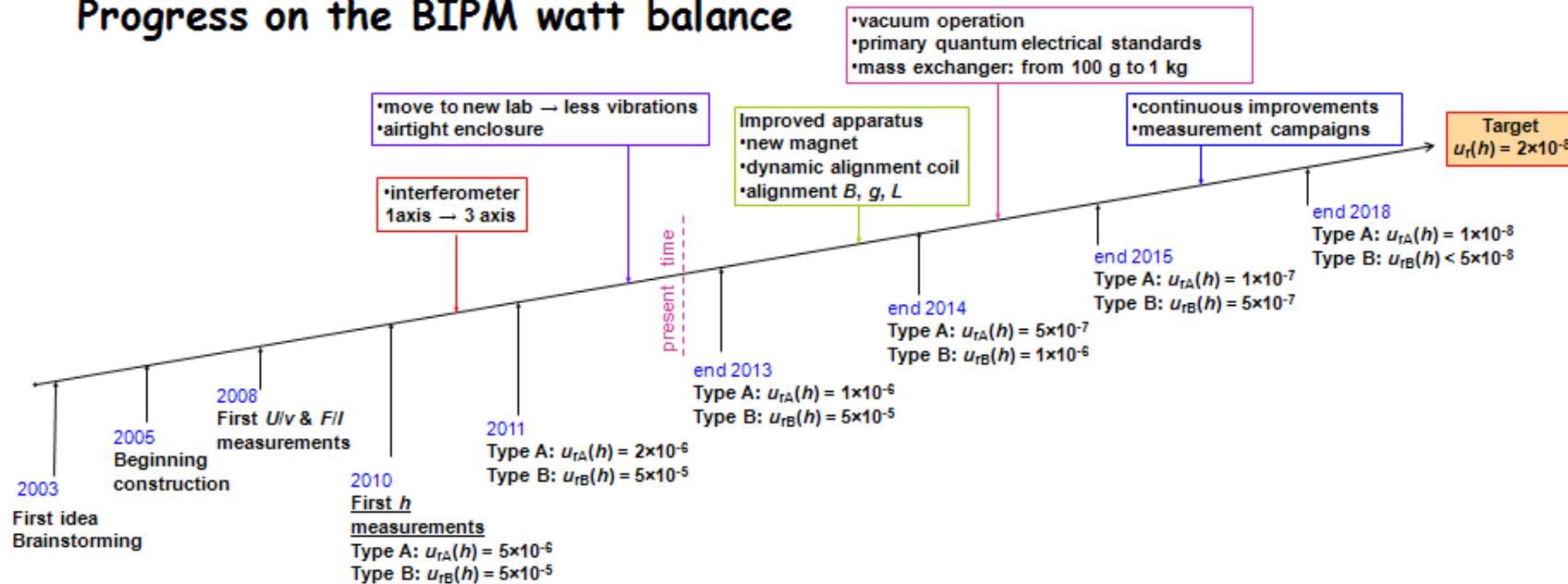
Further reduction

- “ 28 Hz peak
→ stiffer coil (Macor)
- “ residual non-linearity error
→ new interferometer
- “ vibration noise
→ investigation under way
- “ phase resolution
→ better phase detection
- “ ..etc.

Force measurement



Progress on the BIPM watt balance



Next steps

- assembly of the new magnet **done**
- integration of new measurement facilities
- vibration reduction (repl. of air cond.)
- new stiffer coil **done**
- new alignment reference
- next h measurements spring 2014
- new interferometer (2014)

BIPM watt balance team

Full-time



Hao Fang
principal physicist



Adrien Kiss
engineer



Thomas Lavergne
engineer
(mechanics, since May
2013 for 2 years)

Part-time



Michael Stock
(project leader;
magnet)



Lennart
Robertsson
(interferometry)



Estefania de
Mirandés
(coil alignment,
gravimetry)



Stéphane Solve
(JVS)



Régis Charamy
(JVS)

